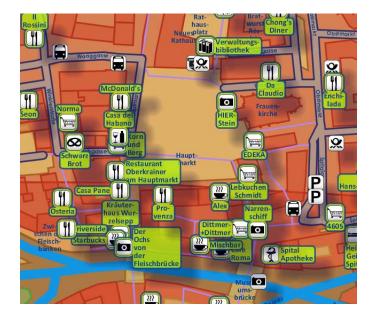
Managing Geo Data – Usage of Open Street Map for Own Services and Applications

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- Applications that consider the user's current location:
- Tour guides
- Route planning (car, tourist)
- Where is...?
- Community services, social networks

Not only end-consumers:

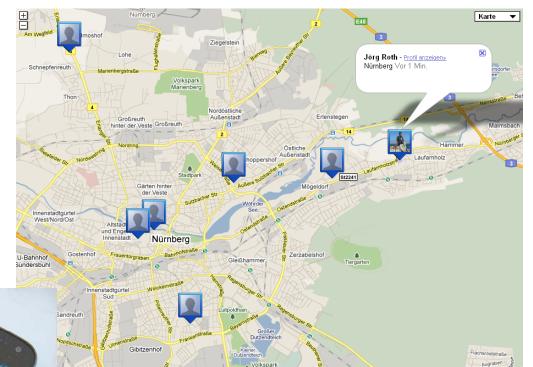
- Market research
- Logistics
- Traffic planning





Service platforms, e.g. Google Maps:

- Map display
- Routing
- Address resolution
- Friend finders
- Mobile support



Why not simply using such a service platform?

- Only services that are available can be used no modifications possible
- Services can be withdrawn
- Costs, licenses
- Service availability (access via mobile networks often a problem)
- No control over geo data
 - Quality or coverage of geo data
 - Not possible to change or add own data

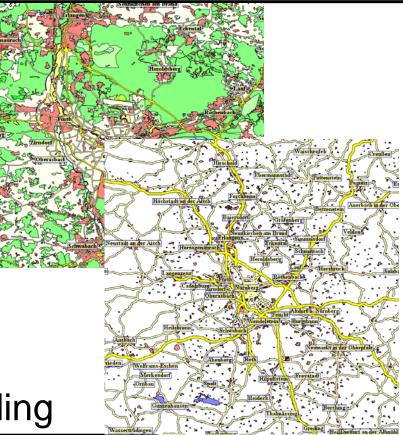
Sometimes, we do not want to rely on other services



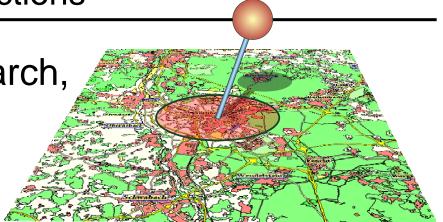
Typical functions

What to do with geo data?

- Paint maps
- Routing
 - shortest, fastest
 - car, pedestrian
 - also useful: train, bus (problem: timetables)
- Geocoding, reverse geocoding
 - geocoding: geo object \rightarrow coordinate
 - reverse geocoding: coordinate → geo object (or → postal address)



- Radius search, nearby search, city search:
 - Where is the nearest fuel station?



- Where are hotels with a distance not exceeding 5 km?
- Give me all parks in Lisbon.
- Spatial join:
 - Give me all open air baths in Bavaria that are close to a train station (nearer than 1km).
 - How many cities in Europe have rivers running through them?

Three major properties of geo data:

- Geometry: what is the shape and location of the object?
- Topology: how is an object related to other objects? (most important: street routing network)
- Thematic properties:
 - Object type, e.g. street, forest, lake, church, bus stop, bistro, tree, artwork...
 - Names

 (in different languages, for different purposes)
 - Further properties: opening hours, max. speed, tree species, restaurant type

We now focus on *vector* data

- Object geometries are points, line strings or polygons
- Also possible: Bezier curves or splines (usually not supported)



Typically 2D (only plane) or 2.5D (height is an attribute), not full 3D

Open Street Map:

 A community project to collect, process and distribute world-wide geo data



- First ideas in 2004
- 2006: Open Street Map Foundation, operable infrastructure
- 2011: 1.2 billion points, 116 million ways,
 1.1 million relations

Sources:

- Privately collected GPS tracks, entered, processed and classified by participating users
- Open geo databases, e.g. the TIGER databases
- Aerial images used to manually georeference objects
- Users can enter objects without any GPS measurement only in relation to existing objects

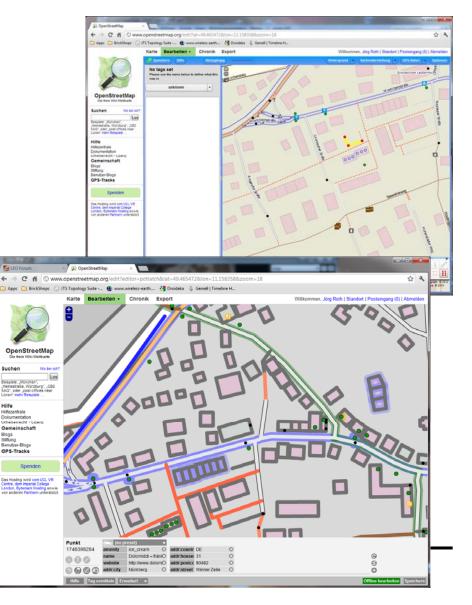


Ways to add data to Open Street Map:

- Online editors
- Stand alone editors
- Registration required

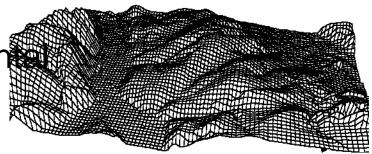
Online discussion (Wiki):

- Most important issues: How to classify objects? (see later)
- Also: workflow, process models



Available data:

- Most important: vector data in 2D
- Map bitmaps (many renderers, also 3rd party) not the original domain of OSM
- Not or only partly supported:
 - Height profiles: only experimented
 - Street topologies: can be derived from geometries



- Is-in relationship: only if users enter tags
- Postal addresses: only if users enter tags

Ways to access vector data from Open Street Map:

- Online via HTTP only small amounts of data
- Planet files:
 - Export of the entire OSM database as XML
 - Also parts in different granularities available: continents, countries, states, districts

→ C ↑ So download.geofabrik.de/osm/ ps BrickShops 137 Stopolog/suite 6% www.wireless-earth				
its.				
	Name	Last modified	Size	Description
	Parent Directory		-	
	africa/	05-Jul-2012 05:52	-	
	asia/	05-Jul-2012 05:53	-	
	<u>australia-oceania/</u>	05-Jul-2012 05:12	-	
	central-america/	05-Jul-2012 05:51	-	
	europe/	05-Jul-2012 10:58	-	
	north-america/	05-Jul-2012 01:24	-	
	south-america/	05-Jul-2012 01:26	-	
ġ	africa.osm.bz2	04-Jul-2012 05:30	362M	OpenStreetMap data, bzip2 compressed
Ø	africa.osm.pbf	05-Jul-2012 01:50	215M	OpenStreetMap data, protobuf binary format
Ø	asia.osm.bz2	04-Jul-2012 06:24	2.6G	OpenStreetMap data, bzip2 compressed
ġ	asia.osm.pbf	05-Jul-2012 01:50	1.7G	OpenStreetMap data, protobuf binary format
0	australia-oceania.osm.bz2	04-Jul-2012 05:31	369M	OpenStreetMap data, bzip2 compressed
ġ	australia-oceania.osm.pbf	05-Jul-2012 01:50	215M	OpenStreetMap data, protobuf binary format
0	central-america.osm.bz2	04-Jul-2012 05:48	196M	OpenStreetMap data, bzip2 compressed
ġ	central-america.osm.pbf	05-Jul-2012 01:24	121M	OpenStreetMap data, protobuf binary format
9	europe.osm.bz2	04-Jul-2012 07:24	12G	OpenStreetMap data, bzip2 compressed
0	europe.osm.pbf	05-Jul-2012 01:50	8.1G	OpenStreetMap data, protobuf binary format
9	south-america.osm.bz2	04-Jul-2012 05:59	453M	OpenStreetMap data, bzip2 compressed
ġ	south-america.osm.pbf	05-Jul-2012 01:24	287M	OpenStreetMap data, protobuf binary format

Nicht das Richtige dabei? Die Geofabrik berät Sie gern oder fertigt spezielle Auszüge für Sie an. Sprechen sie mit uns!

OSM files

OSM files:

- bzip2 compressed (zip not possible due to size limitations)
- unpacked: XML
- Main structure <osm>...</osm>
- Inside: three types of entries (in this order)
 - Nodes: <node>...</node>: Point objects and line points
 - Ways: <way>...</way>:
 Objects with line string or area geometries
 - Relations: <relation>...</relation>: Objects that are built up by other objects



Example: Germany.osm (May 2012)

bzip2 file size	2 GB
XML file size	22 GB
XML tags total	318,532,216
nodes	100,475,499
ways	14,996,507
relations	234,273

OSM XML file (nodes)

```
<?xml version='1.0' encoding='UTF-8'?>
<osm version="0.6" generator="pbf2osm">
<node id="1" lat="51.2492152" lon="9.4317166" version="6"</pre>
     user="elllit" uid="24852"
     timestamp="2011-08-16T11:26:47Z"/>
<node id="10" lat="51.3806531" lon="9.3599172"</pre>
     version="5" user="max60watt" uid="134914"
     timestamp="2011-04-26T20:50:36Z"/>
<node id="12" lat="51.3400316" lon="9.4819956"</pre>
     version="2" user="max60watt" uid="134914"
     timestamp="2011-04-28T21:39:02Z"/>
<node id="13" lat="51.3731042" lon="9.5130058"</pre>
     version="2" user="max60watt" uid="134914"
     timestamp="2011-05-08T22:06:06Z">
       <tag k="highway" v="bus stop" />
       <tag k="name" v="Bleichplatz" />
       <tag k="shelter" v="ves" />
</node>
. . .
```

```
<way id="3591699" version="2" user="Bube"
   timestamp="2009-06-13T07:45:37Z">
     <nd ref="17410365"/>
     <nd ref="17410355"/>
     <tag k="created by" v="JOSM" />
     <tag k="highway" v="track" />
     <tag k="tracktype" v="grade2" />
</way>
<way id="3593390" version="8" user="kanu quenni"</pre>
   timestamp="2010-03-31T18:19:412">
     <nd ref="14539664"/>
     <nd ref="14556238"/>
     . . .
     <nd ref="14539666"/>
     <taq k="bicycle" v="official" />
     <tag k="foot" v="official" />
     <tag k="highway" v="path" />
</way>
. . .
```

```
<relation id="330" version="6" uid="161619" user="FvGordon"
   timestamp="2012-02-24T23:13:40Z">
     <member type="way" ref="49022711" role="inner"/>
     <member type="way" ref="24808645" role="outer"/>
     <tag k="area" v="yes" />
     <tag k="highway" v="pedestrian" />
     <tag k="name" v="Martin-Luther-Platz" />
     <tag k="type" v="multipolygon" />
</relation>
<relation id="2235" version="6" uid="39381" user="DD1GJ"</pre>
   timestamp="2009-11-22T08:15:27Z">
     <member type="way" ref="4917826" role=""/>
     . . .
     <member type="way" ref="7942741" role=""/>
     <tag k="name" v="Lichtentaler Allee" />
     <tag k="route" v="road" />
     <tag k="type" v="route" />
</relation>
</osm>
```

Nodes:

- Major property: latitude/longitude, no extent
- Two types (only implicitly defined):
 - Point-like objects (often called *Point of Interests*): Objects as such, e.g. shop, restaurant, traffic light, postbox, waste container
 - Part of a line string (i.e. only a coordinate)
- Point of Interests must have further properties to be useful
 - at least the object type

<node id="13" lat="51.3731042" lon="9.5130058" version="2" user="max60watt" uid="134914" timestamp="2011-05-08T22:06:06Z"> <tag k="highway" v="bus stop" /> <tag k="name" v="Bleichplatz" /> <tag k="shelter" v="yes" /> </node>

Tags k, v:

k="..." and v="..." are used to express nongeometric properties, e.g.

```
<tag k="highway" v="bus_stop" />
<tag k="name" v="Bleichplatz" />
<tag k="shelter" v="yes"
```

- Details of tagging see later
- For now: we write

instead of

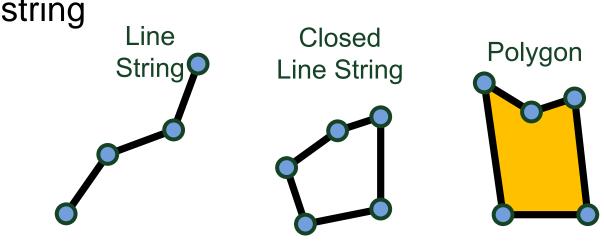
```
<tag k="abc" v="xyz" />
```

OSM ways

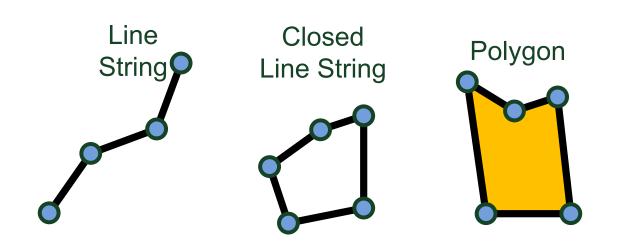
Ways:

A sequence of nodes, referred by their ID

- Usually complete geo objects, i.e. with properties
- Three possible geometries:
 - (open) line string
 - closed line string
 - polygon

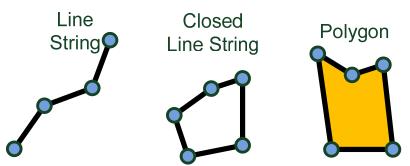


- Open line string: geo objects such as streets
- Closed line string: the actual object is the line string, not the content, example: roundabout
- Polygon: the actual object is the content area, not the border line. Examples: park, forest, lake

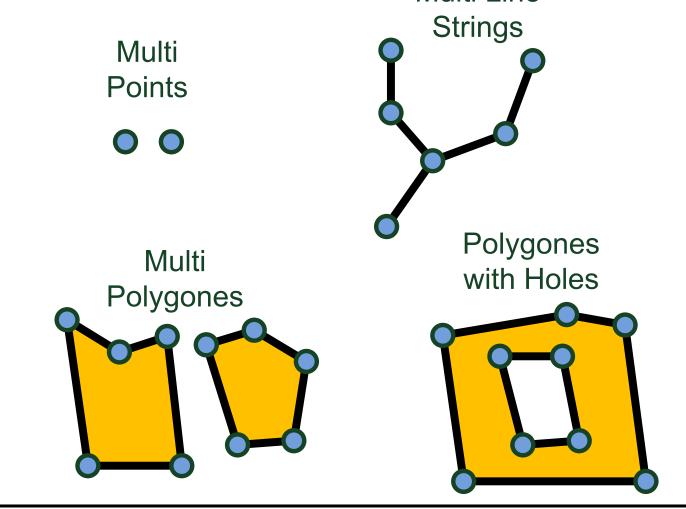


How to distinguish these geometries:

- Open line string: first and last node are not equal
- Closed line string vs. polygon (area):
 - no simple rule
 - sometimes distinguishable by their type
 - -highway usually is closed line string
 - building usually is polygon
 - sometimes optional tag area="yes"



OSM nodes and ways cannot express these geometries: Multi Line



OSM relations

<tag k="area" v="yes" />

<tag k="highway" v="pedestrian" />

<tag k="type" v="multipolygon" />

<tag k="name" v="Martin-Luther-Platz" />

<member type="way" ref="24808645" role="outer"/>

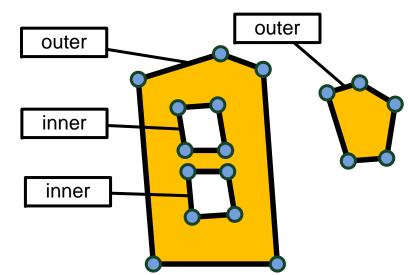
Relations:

- Increase the ability to express complex objects and complex geometries
- Types of relations:

Complex geometries	e.g. polygons with holes, multiple polygons
Objects that share parts to avoid redundancy	e.g. shared borders of two cities
Combine objects to 'bigger' objects	e.g. 'Hiking trail Frankonia to Baltic Sea' that contains smaller hiking trails
Objects with piecewise defined properties	e.g. a highway with different speed limits (note: a way entry can only have a single set of properties)
Relationship between objects	e.g. a turn restriction between roads at a certain crossing

Multipolygon and polygons with holes:

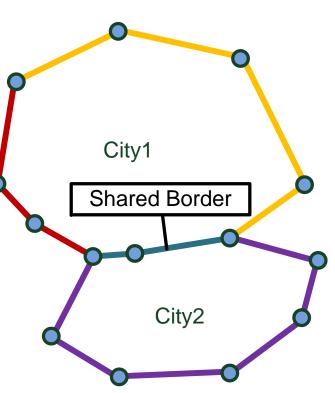
- Relations with tag type="multipolygon"
- Each member must be a closed linestring
- Each member should have role="outer" (a shell) or role="inner" (a hole)
- Unfortunately: no expression which hole belongs to which shell



type="Multipolygon"

Borders:

- Borders (e.g. city borders) are often a collection of lines, each of it representing a part of the border
- Reason: shared borders should only be stored once
- The problem: neither ordering nor orientation are specified in the member description
- Difficult to create a city area from borders



OSM object IDs:

- nodes, ways and relations have unique IDs
- They do not change over time, i.e. can be used to identify objects between imports
- Note: they are only unique inside a type (nodes, ways, relations)
 - node with ID 1 and way with ID 1 possible
 - to have unique object IDs for all types you have to artificially distinguish types, e.g.

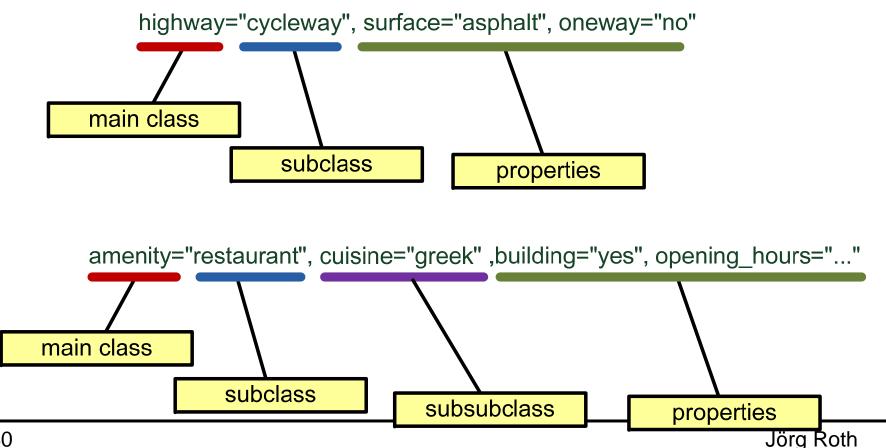
<u> </u>	
$ownID = ID \cdot 3 + 0$	for nodes
$ownID = ID \cdot 3 + 1$	for ways
$ownID = ID \cdot 3 + 2$	for relations

Tagging:

- Users can assign *arbitrary* pairs of key/value to objects
 - no limits for number of pairs
 - no obligatory keys, to superset of keys
 - all values allowed that can be expressed as string
- Only recommendations:
 - you may ask the editor for useful keys
 - no technical check, if entries are useful
- Currently, one problem for automatic classification

However, there is some structure:

- usually there is a most important key/value
- unfortunately, not syntactically indicated



There are keys that define main classesTraffic

Main Class	Subclass example	Description
highway=""	highway="motorway"	Streets, roads, paths
railway=""	railway="station"	Train stuff
cycleway=""	cycleway="lane"	Cycling
waterway=""	waterway="river"	Water
aeroway=""	aeroway="terminal"	Flying
junction=""	junction="roundabout"	Junctions

Buildings, amenities, shops etc.

Main Class	Subclass example	Description
amenity=""	amenity="restaurant"	Amenities
shop=""	shop="hairdresser"	Shops
craft=""	craft="plumber"	Craft
office=""	office="lawyer"	Offices
barrier=""	barrier="bollard"	Barriers, walls
man_made=""	man_made="water_tower"	Special buildings
power=""	power="generator"	Electricity
military=""	military="bunker"	Military

Countryside, nature

Main Class	Subclass example	Description
natural=""	natural="rock"	Anything natural
landuse=""	landuse="farm"	Agriculture, farms
geological=""	geological="valley"	Geological formations

Non-physical objects

Main Class	Subclass example	Description
route=""	route="bus"	Sequence of ways
boundary=""	boundary="postal_code"	Boundaries, e.g. city
place=""	place="county"	Captions, labels

Leisure, tourism

Main Class	Subclass example	Description
sport=""	sport="golf"	Places for sport
leisure=""	leisure="park"	Places for leisure
tourism=""	tourism="hostel"	Related to tourism
historic=""	historic="monument"	Historic objects

(list is not complete)

- For some classes, further classes are recommended, e.g. for amenity="restaurant" a further tag cuisine="..." (e.g. cuisine="bistro") is expected
- The problem:
 - it is not clear, whether a tag is meant as classification (such as 'cuisine') or as property (such as 'opening hours')
 - rule-based analyses required to map classes to objects

Ambiguity

Ambiguity:

- Three ways to express 'bistro'
 - shop="bistro"
 - amenity="bistro"



- amenity="restaurant",cuisine="bistro"
- Two ways to express combined foot/cycleway
 - highway="cycleway", footway="yes"
 - highway="footway", cycleway="yes"
- To quickly distinguish object types (e.g. for routing), a simpler classification scheme is required in own databases

Tags to name objects:

Тад	Meaning	Example
name=""	Standard name	Germany
name:de=""	Name in different languages	Deutschland
*_name=""	*∈{int, nat, loc, reg} international, national, local or regional name	Bayern
<pre>short_name=""</pre>	Common abbreviation	UK
official_ name=""	Official name	Principality of Andorra

Further tags for naming:

Тад	Meaning	Example
ref=""	Name of motorways, bus lines etc.	A1, Route 66, 23
*_ref=""	*∈{int, nat, loc, reg} international, national, local or regional name	A1 (without blank), A 1 (with blank)
addr: housename=""	House name as part of address information	Hotel 4 Seasons

Defining postal addresses:

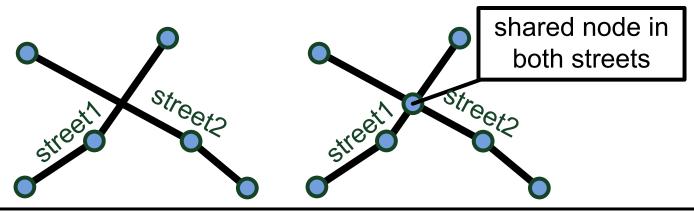
Тад	Meaning	Example
addr: country=""	Country code as used in Internet names	DE
addr: city=""	Local city name	Nürnberg
addr: postcode=""	Postcode	90489
addr: street=""	Street	Kesslerplatz
addr: housenumber=""	House number	12
addr: housename=""	House name	Gebäude A

Where is an object located semantically?

- In which city, state, country resides an object?
- Can in principle derived by
 - border geometries: area required, geometric check is time consuming
 - postal addresses: not every relationship is encoded in the postal address (e.g. suburbs, districts in town, villages)
- Object can have explicit is_in tags, e.g. is_in="Nuremberg"
 - controversially discussed
 - not consistently used

Street topologies:

- Not actually supported by OSM
- The street network can be derived from street geometries:
 - if streets are connected, they must have a shared node
 - if crossing streets that are *not* connected (bridges, tunnels), they *must not* have a shared node



Tags that affect route planning:

Tag	Meaning	Example
oneway="yes"	Driving only possible in the given direction	
maxspeed=""	Speed limit	50, 60 mph
highway=""	Street type	residential, secondary, motorway

In addition:

- Information about traffic signs, traffic lights
- Relations can identify turn restrictions

Public Transportation:

- Stops and stations are stored
- Connections are also available
 - typically as relations of streets or tracks
- The problem: no timetables available

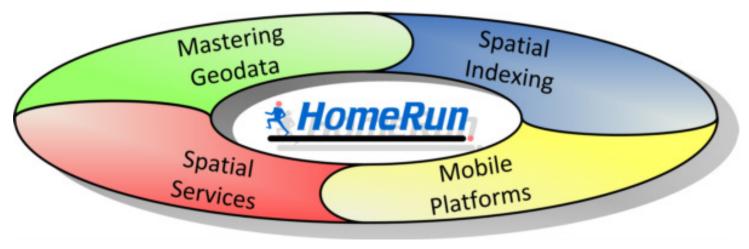


The *HomeRun* environment:

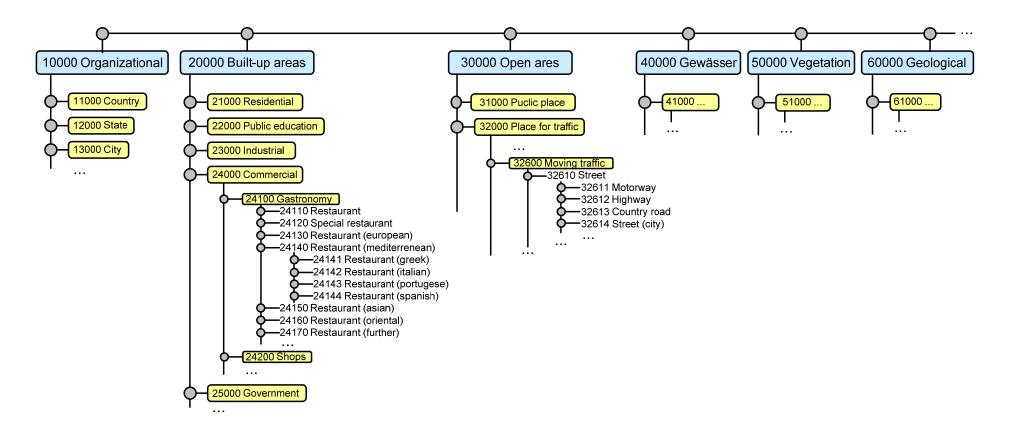
Import, management, access of large amounts of geo data



- Also: foundation for spatial services, support for mobile platforms
 - dorenda map renderer and viewer
 - donavio navigation environment



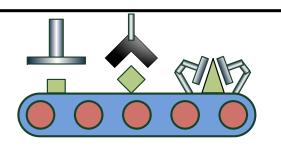
- Objects are classified by a 5 digit number
- Implicitly: a tree



HomeRun OSM import

The HomeRun import chain:

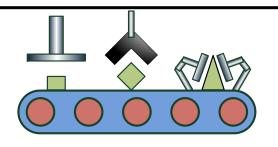
Parse XML



- Replace all references to nodes and ways by their geometry
 - Following references during a query is too time consuming
- Classify objects (rule-based):
 - Define the classification number
 - Decide geometry (esp. closed line string vs. area)
 - Find out the appropriate (best) name
 - Distinguish tags (names, address, is-in, links, organizational)

HomeRun OSM import

- Resolve relations:
 - Build multipolys with holes
 - Build areas from line string borders
- Prepare route planning:
 - Compute the street topology from geometries
 - Retrieve routing relevant properties (oneway, maxspeed, avgspeed)
- Compute is-in relationship:
 - Detect import larger objects (city, state etc.)
 - Geometrically check if 'inside'



How HomeRun stores geo data:

- Postgres database without spatial extension
 - geometries stored as Well-known-binary (WKB) in BLOBs
 - own spatial index (*Extended Split Index*)
- Also conceivable: SQL databases with spatial extension (e.g. PostGIS)
- HomeRun supports mobile devices
 - spatial extension to SQLite
 - spatially indexed virtual memory arrays (called spatial hashtables)

Rendered maps with *dorenda*



How to start?

- 1. Enter some data into OSM this is useful to get an idea of the process and structure.
- 2. Browse through the OSM Wiki to learn about object classifications.
- *3.* For the first step, concentrate on a specific task, e.g. map painting, route planning.
- **4.** Create an OSM XML parser (a simple one is sufficient). Be sure, the parser does not read the entire file before analyzing it.

- 5. Replace references to nodes by their coordinate following references at runtime is too time consuming.
- 6. From the beginning, use a database (a non-spatial often is sufficient) using files will only work for small regions.
- 7. From the beginning use a geometry library. Don't reinvent the wheel geometric computation is challenging.

- 8. Use an own classification schema (e.g. based on a number) the OSM way to classify objects is too complex at runtime.
- 9. Think about rule-based classification and name finding (simple rule execution will be sufficient).

10.In early stages – forget relations. They are very complex to analyze, often inconsistently stored and often not useful.



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